

Efficient Convex Zone Merging in Parametric Timed Automata

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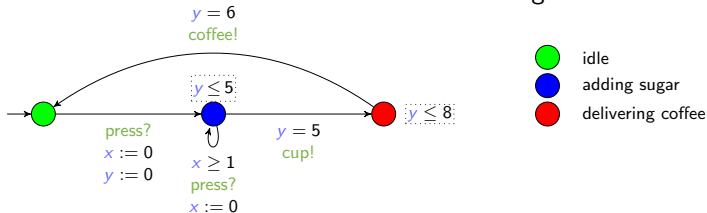
³ Aarhus University, Aarhus, Denmark

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Timed Automaton (TA)

- ▶ Finite state automaton (sets of **locations** and **actions**) augmented with
 - ▶ a set X of **clocks** [AD94]
 - ▶ Real-valued variables evolving linearly **at the same rate**
 - ▶ Can be compared to integer constants in invariants and guards
- ▶ Features
 - ▶ Location **invariant**: property to be verified to stay at a location
 - ▶ Transition **guard**: property to be verified to enable a transition
 - ▶ Clock **reset**: some clocks can be **set to 0** along transitions

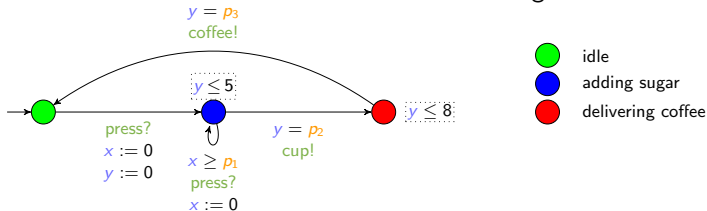


[AD94] Rajeev Alur and David L. Dill. "A theory of timed automata". In: *Theoretical Computer Science* 126.2 (Apr. 1994), pp. 183–235. ISSN: 0304-3975. DOI: 10.1016/0304-3975(94)90010-8

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Parametric Timed Automaton (PTA)

- ▶ Finite state automaton (sets of **locations** and **actions**) augmented with
 - ▶ a set X of **clocks** [AD94]
 - ▶ Real-valued variables evolving linearly **at the same rate**
 - ▶ Can be compared to integer constants in invariants and guards
 - ▶ a set P of **parameters** (**unknown constants**) [AHV93]
- ▶ Features
 - ▶ Location **invariant**: property to be verified to stay at a location
 - ▶ Transition **guard**: property to be verified to enable a transition
 - ▶ Clock **reset**: some clocks can be **set to 0** along transitions



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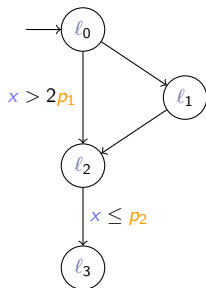
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Parametric Zone Graph (PZG)

- ▶ **Symbolic state**: a pair with a location and an attached parametric zone (constraint)
- ▶ **Parametric zone**: a set of valuations defined by conjunctions of constraints on clocks and parameters

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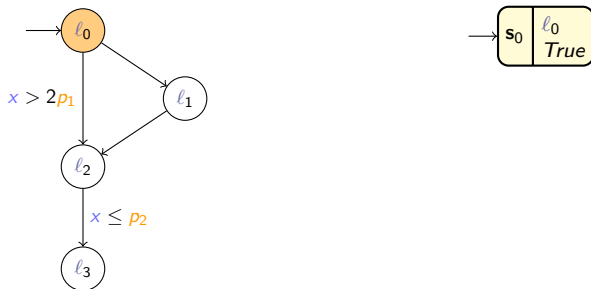


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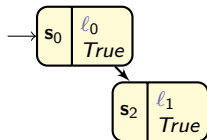
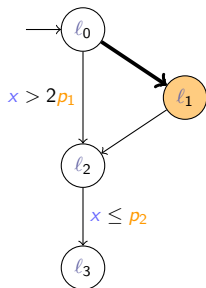


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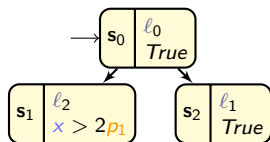
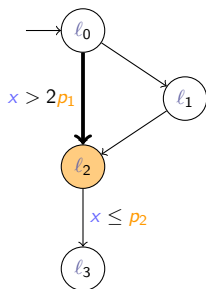


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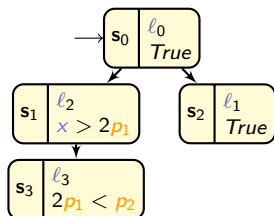
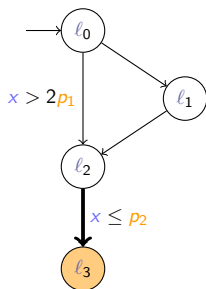


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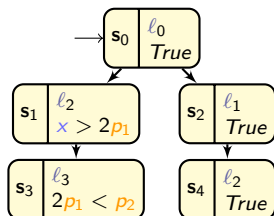
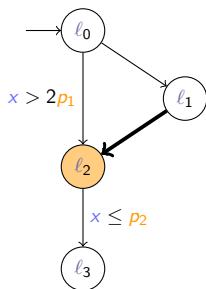


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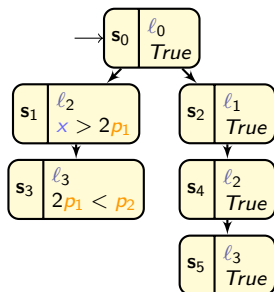
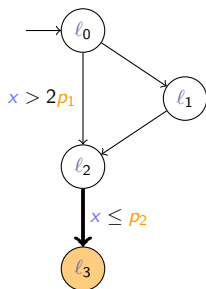


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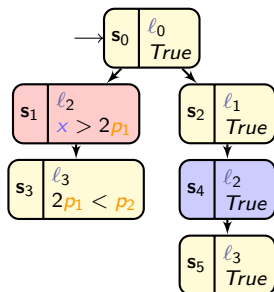
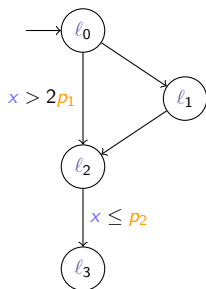


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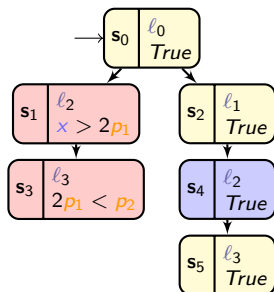
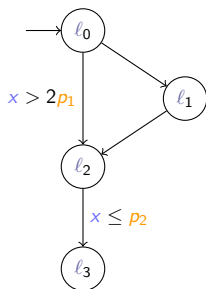


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Merging states

Definition

Two states (\bullet, \mathbf{C}_1) and (\bullet, \mathbf{C}_2) are **mergeable** if:

▶ $\bullet = \bullet$

▶ $\mathbf{C}_1 \cup \mathbf{C}_2$ is convex

Their merging is defined by $(\bullet, \mathbf{C}_1 \cup \mathbf{C}_2)$

[Dav05] Alexandre David. "Merging DBMs Efficiently". In: *NWPT* (Oct. 19–21, 2005). DIKU, University of Copenhagen, 2005, pp. 54–56

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State merging techniques were introduced:

- ▶ in TA [Dav05]
- ▶ in PTA for Inverse Method [AFS13]

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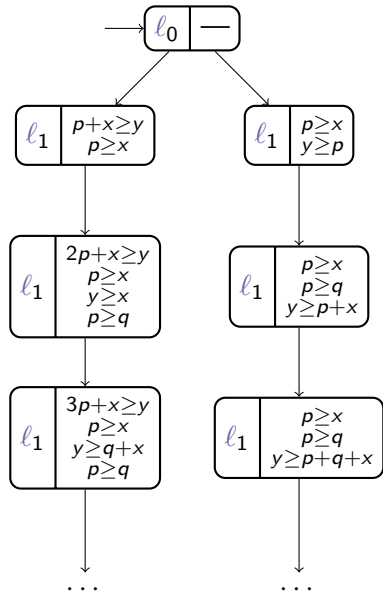
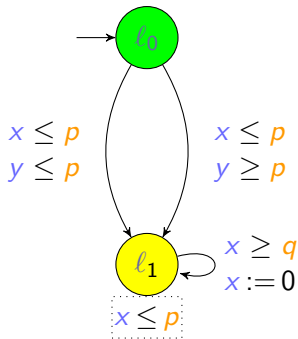
Merging preserves reachability

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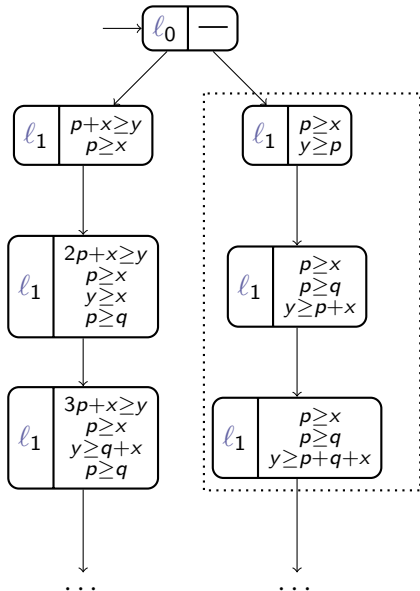
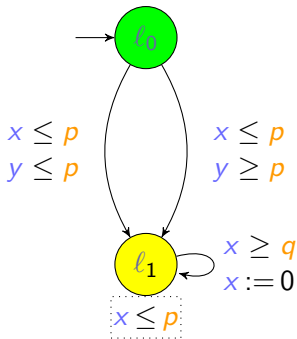
Merging can make difference for termination!

PZG without any heuristic



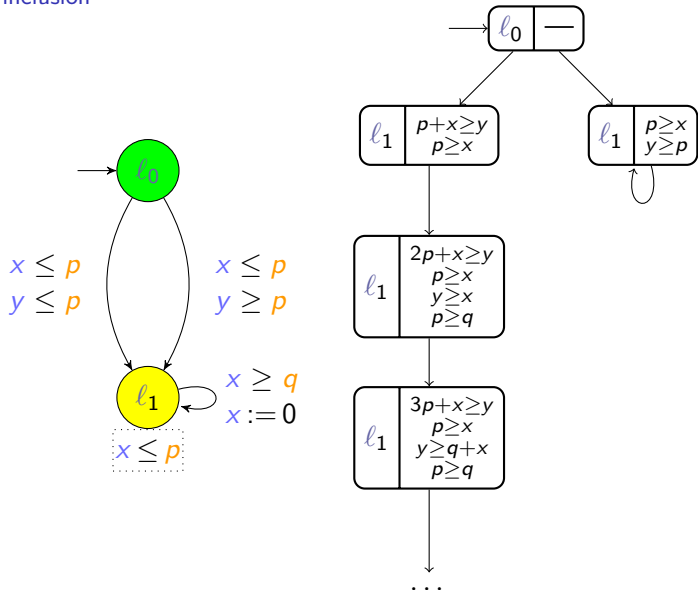
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PZG with inclusion



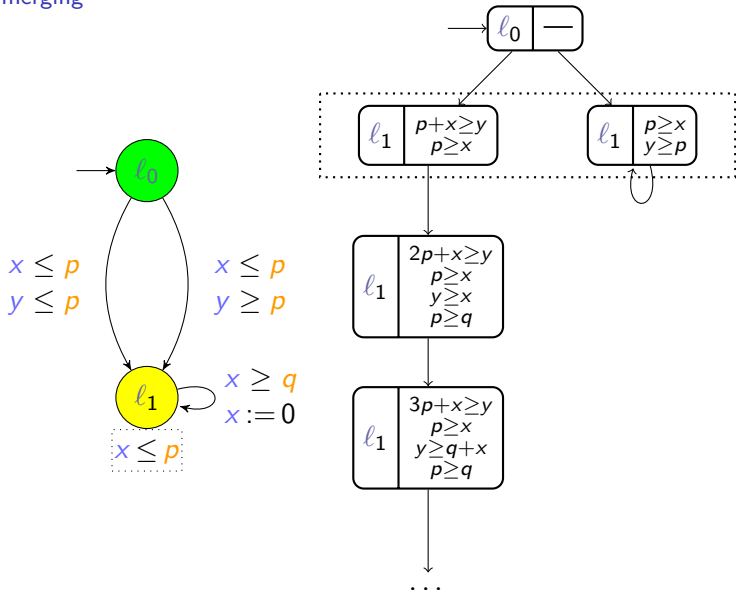
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PZG with inclusion



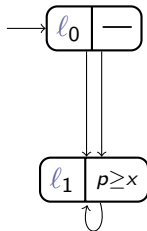
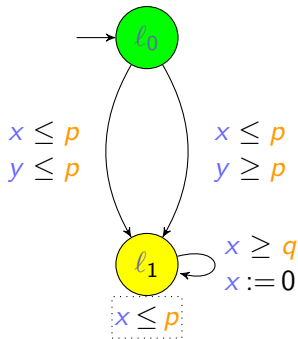
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PZG with merging



Merging can make difference for termination!

PZG with merging



The construction of the PZG

Algorithm 1: BFS by layer $\text{layerBFS}(\mathcal{A})$

```
1 Visited  $\leftarrow \{s_0\}$ 
2 Queue  $\leftarrow \{s_0\}$ 
3  $\Rightarrow \leftarrow \emptyset$ 
4 while Queue  $\neq \emptyset$  do
5   Qnew  $\leftarrow \emptyset$ 
6   foreach s  $\in$  Queue do
7     foreach  $(e, s') \in \text{SuccE}(s)$  do
8       Qnew  $\leftarrow \mathbf{Q}_{new} \cup (\{s'\} \setminus \mathbf{Visited})$ 
9        $\Rightarrow \leftarrow \Rightarrow \cup \{(s, e, s')\}$ 
10  Visited, Queue  $\leftarrow \text{mergeSets}(\mathbf{PZG}, \mathbf{Visited}, \mathbf{Q}_{new})$ 
```

Heuristics for merging

What to merge with what? Queue, Visited, Ordered
Restart after merge?

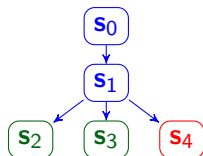
When to update the state space?

- ▶ After each merge
- ▶ After exploring the candidates list
- ▶ After exploring a BFS level

How to update the state space?

- ▶ Reconstruction of the state-space
- ▶ *In situ*

Illustration of the merging options



- visited
- in the queue
- being processed
- after merge

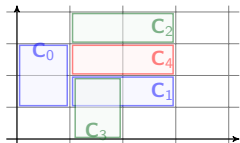
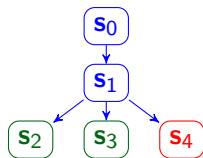
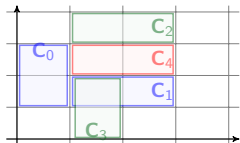


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Merge with Queue

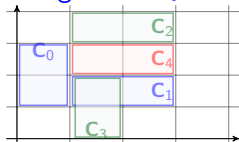
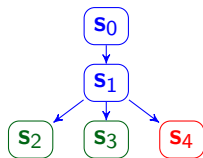
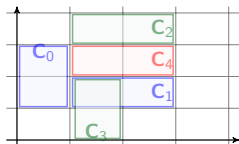


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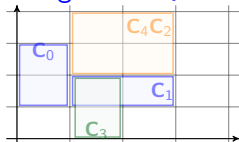
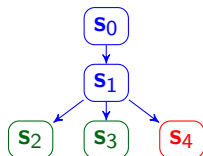
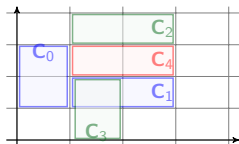


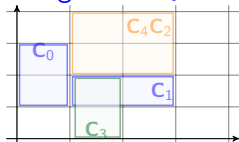
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Merge with Queue



Merge with Visited

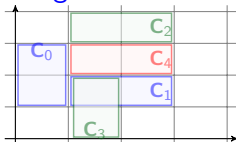
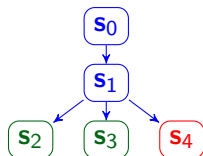
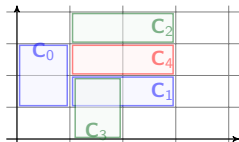


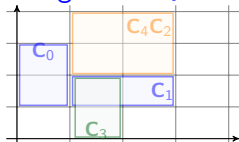
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Merge with Queue



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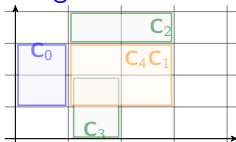
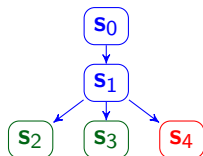
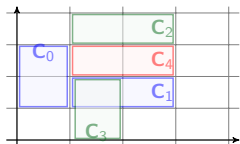


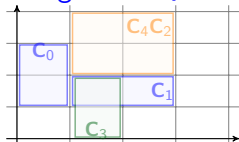
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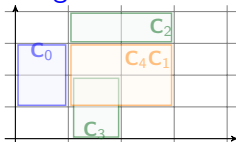
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Merge with Queue



Merge with Visited



and Restart

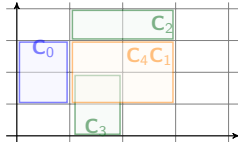
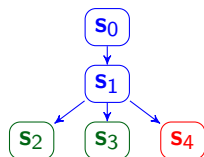
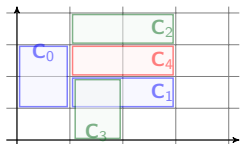


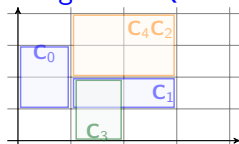
Illustration of the merging options



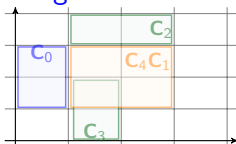
- visited
- in the queue
- being processed
- after merge



Merge with Queue



Merge with Visited



and Restart

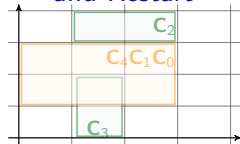
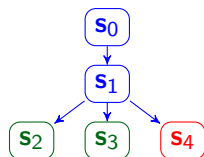
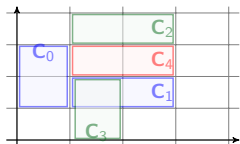


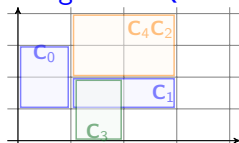
Illustration of the merging options



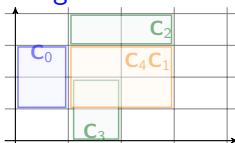
- visited
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- being processed
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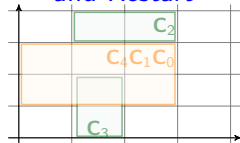
Merge with Queue



Merge with Visited



and Restart



Queue ; Visited

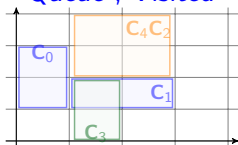
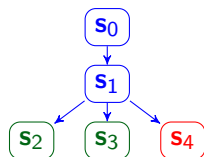
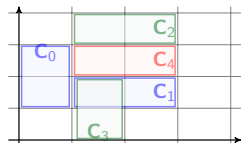


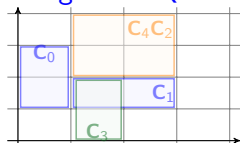
Illustration of the merging options



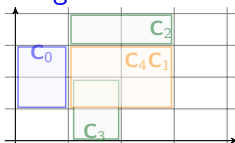
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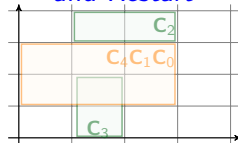
Merge with Queue



Merge with Visited



and Restart



Queue ; Visited

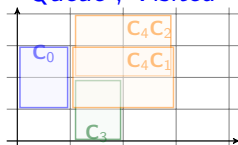
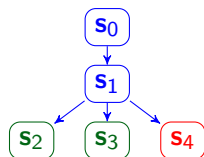
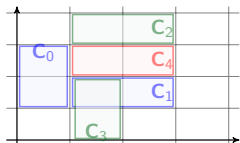


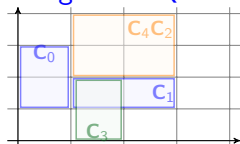
Illustration of the merging options



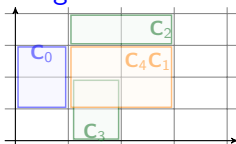
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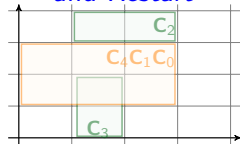
Merge with Queue



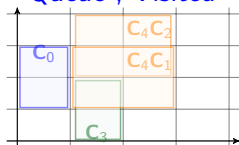
Merge with Visited



and Restart



Queue ; Visited



Update after Merge

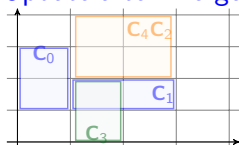
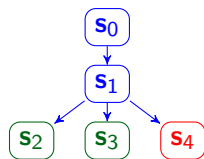
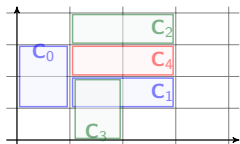


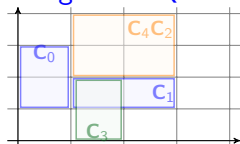
Illustration of the merging options



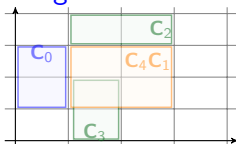
- visited
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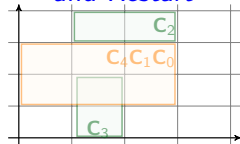
Merge with Queue



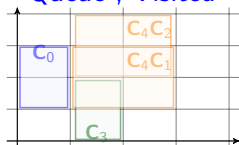
Merge with Visited



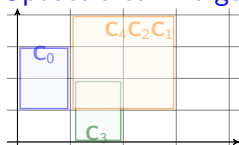
and Restart



Queue ; Visited



Update after Merge



Experiments

- ▶ Comparison of all the combinations of heuristics
- ▶ Use of the IMITATOR library, restricted to reachability-based properties [AMP21]:
 - ▶ 124 executions (model, reachability property)
 - ▶ 42 executions perform at least one merge

[AMP21] Étienne André, Dylan Marinho, and Jaco van de Pol. “A Benchmarks Library for Extended Timed Automata”. In: *TAP* (June 21–25, 2021). Ed. by Frédéric Loulergue and Franz Wotawa. Vol. 12740. LNCS. virtual: Springer, 2021, pp. 39–50. DOI: 10.1007/978-3-030-79379-1_3

Results

		Nomerge	M2.12	RVMr	OQM
Time	# wins	24	20	22	42
	Avg (s)	10.0	5.47	4.56	3.77
	Avg (merge) (s)	18.8	7.83	5.57	3.63
	Avg (no merge) (s)	3.83	3.82	3.85	3.88
	Median (s)	1.39	1.2	1.14	1.12
	Norm. avg	1.0	0.91	0.91	0.87
	Norm. avg (merge)	1.0	0.75	0.74	0.64
	Norm. avg (no merge)	1.0	1.02	1.03	1.03
States	# wins	0	19	37	16
	Avg	11443.08	11096.54	11064.37	11120.79
	Avg (merge)	1512.02	670.43	592.31	729.33
	Median	2389.5	703.5	604.5	905.0
	Norm. avg	1.0	0.86	0.84	0.88

Conclusion and Perspectives

- ▶ investigated the merge operation for reachability analysis in PTAs
- ▶ proposed several heuristics
- ▶ shown they are sound
- ▶ extensive experiments to compare these approaches

Conclusion and Perspectives

- ▶ investigated the merge operation for reachability analysis in PTAs
 - ▶ proposed several heuristics
 - ▶ shown they are sound
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-
- ▶ tackle the handling of merged states:
 - ▶ pruning away
 - ▶ separate collection of potential mergers
 - ▶ merge more than 2 states
 - ▶ canonical merge representatives
 - ▶ compatibility of merging and liveness properties

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